l. 一般事项 General

1-1. 适用规格 Scope

本规格适用于微小电流回路的电子设备,属11型回转编码器.

This specification applies to 11 mm size low-profile rotary encoder (incremental type) for microscopic current circuits, used in electronic equipment.

1-2. 标准状态 Standard atmospheric conditions

除另有规定外,测量应在以下状态下进行:

Unless otherwise specified, the standard range of atmospheric conditions for making measurements

and test is as following limits:

温 度 Ambient temperature : 15℃ to 35℃

相对湿度 Relative humidity:25% to 85%

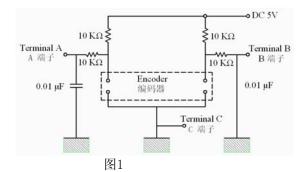
气 压 Air pressure:86kpa to 106kpa

1-3. 使用温度范围

Operating temperature range:-10℃ to 70℃

1-4. 保存温度范围

Storage temperature range: -40℃ to+85 ℃



2. 构造 Construction

2-1. 尺寸 Dimensions

见所附成品图Refer to attached drawing

3. 额定值 Rating

3-1. 额定电压

Rated voltage :DC 5V

3-2. 最大额定电流(阻抗负载)

Maximum operating current (resistive load)

各相导线 Each lead: 1mA)

4. Application Nots 使用上的事项

4-1. 避免储藏于高温、潮湿及腐蚀的场所. 产品购入后尽可能在6个月内使用完. 拆包装后未使用完的剩余 产品需储藏于防潮防毒的环境下.

Avoid storing the products in a place at high temperature, high humidity and in Corrosive gases. Please

use this product as soon as possible with 6 months limitation. If any remainder left after packing is opened,

please store it with proper moisture proofing, gasproofing etc.

4-2. 编码器信号的计算方法应将操作的速度,信号的取样时间及电子回路中的微电脑软体等考虑进去. The encoder pulses count method should be designed with taking operating speed, sampling time and

design of the microcomputer software into cosideration.

4-3. 此产品在定位点的输出阻抗波形参照(5-1), 因此在设计软体时请留意其状态.

With this products the detent position output consult fig. 5-1. Therefore make the A phase the reference

at the soft ware design stage.

4-4. 在设计时要考虑到杂讯,建议使用C/R滤波电路,(图1)

At design of the pulse count process . Using the C/R filter circuit is Recommended (fig. 1)

4-5. 本产品请勿碰触到水,可能会导致输出波形的异常.

Care must be taken not to expose this product to water or dew to prevent possible problem in pluses

output waveform

5.电气性能	ELECTRCAL (CHARACTERIS	TICS		
项目		条件	规格		
ITEM		CONDITIO	SPECICATIONS		
	A、B两信号输出相位差,输出波形详细见(图2/3)(虚线表示带卡点装置的上擎子处位置) 2 phase different signals (signal A, signal B) Details shown in <fig,2 3=""> (the broken line shows detent position.)</fig,2>				
	轴回转方向	信号	1	输出波形	
	Shaft rotati-onal direction	Signal	Output 图 3 fig. 3		
5-1.输出信号 Output signal format	顺时针方向 C.W	(A-C端子间) A(Terminal A-C) B (B-C端子间) B(Terminal B-C)	图 2 fig. 2	OFF ON ON	
	逆时针方向 C.C.W	A(A-C端子间) A(Terminal A-C) B(B-C端子间) B(Terminal B-C)	O FF ON OFF	OFF ON OFF	
	回转360°的输出脉沿			■15个脉冲/360°(图2)	
5-2. 分解能力 Resolution					
5-3.开关特性 Switching characteristics	Measurement shall be Shaft rotational spee 10 KΩ Terminal A A 端子 10 KΩ [6] [6] [6] [6] [6] [6] [6] [6] [6] [6]	图4 <fig .4=""> Encoder 编码器 Termina C 端于 出电压3.5V以上的状</fig>	OFF Corcuit: (fig .4) OFF ΚΩ Terminal B B H ON ON ON Code-OFF area : The are are are are are are are are are ar	rea which the voltage is 3.5Vor more(fig.5) a which the voltage is 3.5Vor more(fig.5).	
5-3-1.振荡 Chattering	编码从OFF→ON或ON→OFF时,输出1.5V~3.5V的通过时间应符合规定. Specified by the signal spassage time from 1.5V to 3.5V of each switching position (code OFF~ON or ON ~OFF)				
(突跳) Sliding noise	编码 ON 部份的1.5V以上的电压变动时间在振荡t1,t3之间会产生1ms以上,1.5V以下的 ON 部份.另外,如果各突跳间1.5V以下的范围在1ms以上时,则判定为另一个突跳. Specified by the time of voltage change exceed 1.5V in code-ON area.when t bounce has code -ON time less than lms between chattering (t1 or t3).the voltage change shall be regarded as a part of chattering.when the code-ON time between 2 bounces is less than lms .they are regarded as 1 linked bounce				
5-3-3.滑动噪音	编码OFF部份的电压变动。 3.5 V 以上				
	The voltage change:		3.5 V min		

5. 电气性能 ELECTRAL CHARACTERISTICS						
项目 ITEM	条件 CONDITIONS	规格 SPECIFICATIONS				
5-4. 相差 Phase difference	下(图6)所示回路,轴以360°/S的速度转动测定。 Measurement shall be made under the condition which the shaft is rotated at 60r/min 图6 fig. 6 A信号(A~C)间 signal A B信号(B~C)间 signal B T1 T2 T3 T4 C.W Direction	T1、T2、T3、T4≥4mS 见图6(fig. 6)				
5-5. 绝缘阻抗 Insulation resistance 5-6. 耐电压 Dielectric	在端子和轴间施加电压 250V DC。 Measurement shall be made under the condition which a voltage of 250V DC is applied between individual terminals and bushing. 在端子和轴间施加 AC 300 V电压1分钟。 A voltage of 300V AC shall be applied for 1 minute between individual terminals and bushing.	100MΩ 以上 100MΩ Min 不得有绝缘破坏 Without arcing or breakdown				
Contact resistance	出力信号处于 ON 时安定状态条件下测定. Measurement shall be stalbe condition which a output signal is ON.	1Ω以下 1ΩMax				
6-1. 全回转角度 Total rotational ar 6-2. 定位点力矩	nanical characteristics Ingle 只适用于附卡点装置	360° (无止档点) 360° (End less) 3~20mN.m(30~200gf.cm)				
Deten torque 6-3.定位点数及位置 Number of detent	Onlt suitable for C.C, equipment. 只适用于附卡点装置	Shaft rotatable at -10℃~+5℃ 但在-10℃~+5℃轴勉强可转动 30detents (Step angle :12° ±2°) ■30点定位(间隔角度12° ±2°)				
and position	Onlt suitable for C. C, equipment.	20detents(Step angle:18° ±2°) □20点定位(间隔角度18° ±2°)				
6-4. 轴的推拉强度 Push -pull stren- gth of shaft	在轴端,沿轴向施加 10Kg 的静负荷力推和拉各10秒钟 (产品焊锡固定在PCB上。) Push and pull static load of 10kg shall be applied to be shaft in the axial direction for 10s. (After soldering of the PC board)	轴无破损,回转无异常,电气性能无异常。 Without damage or excessive play in shaft.NO excessive abnormality in rotational feeling .And.electrical characteristics and be satisfied.				
6-5. 轴摆动 Shaft wobble	在轴前端5mm处,沿径向瞬间施加 50mN.m (500gf.cm)的力. A momentary load of 50mN.m (500gf.cm) shall be applied at the point 5mm from the tip of the shaft in a direction perpendicular to the axis of shaft.	0.8xL/30mm p-p以下(L:指安装 平面到轴的柄端的的距离) 0.8x1/30mm p-p Max或(1:Distance between mounting surface and measuring point on the shaft)				
6-6.轴的回转方向 摆动 Shaft play in rotational wobble	用角度板测定. Testing by angle board.	5°以下 5°MAX				

7. 耐久性能	ENDURANCE CHARACTERISTICS			
项目 ITEM	条件 CONDITIONS	规格 SPECIFICATIONS		
7-1.回转寿命 Rotational life	在无负荷条件下轴以 600周/小时速度回转30,000周。 The shaft of encoder shall be rotated to 30,000 cycles at a speed of 600cycles/H without electrical load, after with measurements shall be made.	端子间接触阻抗200Ω 以下。 Contact resistance 200Ω Max 尚余有轻微定位感 Vibration t1,t3≤5mS 振荡t1,t3 ≤5mS Bounce t2≤5mS 突跳 t2≤ 5mS Detent feeling has to remains		
7-2. 耐湿性 Damp heat	温度40±2℃,湿度90~95%的恒温恒湿湿槽中放置48 小时后,在常温、常湿中放置1.5小时后测试. The encoder shall be stored at temperature of 40±2℃ with relative humidity of 90% to 95% for 48H in a thermostatic chamber. And the encoder shall be subjected to standard atmospheric conditions for 1.5H, After which measurements shall be made.	所有项应满足初期规格 Specifications in clause all items is shall be satisfied .		
7–3. 耐热性 Dry heat	温度80±3℃的恒温箱中放置48小时,然后在常温、常湿放置 1.5小时后测试. The encoder shall be stored at a temperature of 80±3℃ for 48H in a thermostatic chamber. And the encoder shall be subjected to standard atmospheric conditions for 1.5H, After which measurements shall be made.	所有项应满足初期规格 Specifications in clause all items is shall be satisfied .		
7-4. 低温特性 Cold	温度-25±3℃的恒温箱中放置48小时,常温、常湿放置1.5小时后测试. The encoder shall be stored at a temperature of -25±3℃ for 48H in a thermostatic chamber. And then the encoder shall be subjected to standard atmospheric conditions for 1.5H. After which measurements shall be made.	所有项应满足初期规格 Specications in clause all items is shall be satisfied .		
7-5.焊锡性 Solder ability	端子在260℃±5℃温度的焊锡槽内浸锡3秒±0.5秒. The terminals shall be immersed into solder bath at 260 ℃ for 3s±0.5s in the same manner as para.	浸渍面须有75%以上焊锡附着 A new uniform coating of solder shall cover 75% minimum of the surface being immersed.		
7-6.耐焊接热 Resistance to Soldering heat	手工焊接 Manual soldering 温度300℃以下,时间3秒以内. Bit temperature of soldering iron:300℃ less than applicat time of soldering iron :within 3s. 槽焊 Dip soldering . 使用基板: t=1.6mm的单面覆铜板. Printed wiring board :single -stded copper clad laminate board with thickness of 1.6mm. 预热:基板表面温度100℃以下,时间1分钟以内. Preheating:1.Surface temperature of board :100℃ or less 2.preheating time :within 1 min 焊接:温度260±5℃或以下,时间3秒以内. Soldering:Solder temperature:260±5℃ or less Immersion time:within 3s	ion 不得有绝缘体的破坏、变形、 接触无异常. Electrical characteristics shall be satisfied No mechanical abnormality.		

推动开关部分Push Switch Portion

备注:以下规格适用于R11ECS编码带开关系列.

No: The following specification is only suitable for the one type wih switch construction of R11EC encoder series.

1. 额定值Rating

1-1.额定电压

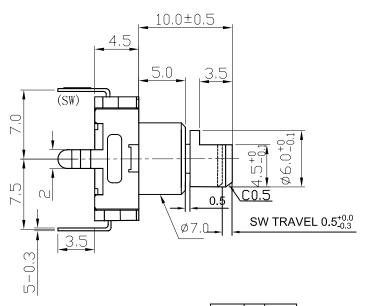
Rated voltage: DC 5V

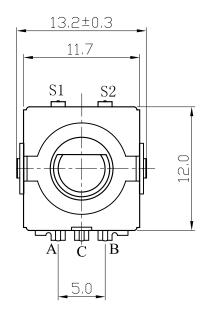
1-2. 最大额定电流(阻抗负载)

Maximum operating current (resistive load):10mA MAX

	CAL CHARACTERISTICS			
项目	条件	规格		
ITEM	CONDITIONS	SPECIFICATIONS		
2-1.接触电阻	用 DC 5V 1mA 电压测定.	100m $Ω$ less $≤ 100$ m $Ω$		
Contact resistance	Voltage test at DC 5V 1mA.	≈ 100m 52		
	在端子和安装板间施加电压250V DC.			
2-2.绝缘阻抗	Measurement shall be made under the condition which a voltage	100MΩ 以上		
Insulation resistance	of 250V DC is applied between individual terminals and bushing	100MΩ Min		
	and bushing and plank			
2-3. 振荡	以1秒钟1往返(OFF-ON-OFF)按压动作.	10ms or less		
Bouncing	Shaft shall be push at I cycles/s (OFF-ON-OFF)	≤10ms		
2-4. 耐电压	在端子和安装板间施加AC300V电压1分钟	不得有绝缘破坏		
Dielectric strength	A voltage of 300V Acshall be applied for I minute between	Without arcing or breakdown		
	individual terminals and bushing and plank.			
3 机械性能 Mechanica	al characteristics			
3-1.开关电路.接点数		单极单投(按压ON)		
Switch circuit and		Single pole and single throw		
number of pulse		(push ON)		
3-2.开关动作力	在轴端,沿轴向施加的按压力.	200~800gf.cm		
Operation fore of switch	Push static load to the shaft in the axial direction.	200~800g1.CIII		
3-3.开关动移动量		0.5±0.3mm		
Travel of switch		0.3±0.3mm		
4 耐久性能 Endurance	Characteristics			
		接触电阻 : ≤200mΩ.		
回转寿命	The shaft of encoder shall be push to 20,000 cycles at a speed of	其它应满足初期规格.		
Rotaional life	600 cycles/H without electrical load ,after with measurements	Contact resistance : $200 \text{m} \Omega$ or less		
	shall be made.	Specifi cation in clause shall be		
	satisfied.			
		<u> </u>		
制定日期	2007-5-15 DSG.承办 CHKD.审核 APPD.批准	TITLE 标题:		
版本号: 00	変更记录 R & D R & D	ENCODER 编码器		
	2009.06.05 2009.06.05	DOCUMENT No.文号:		
	Sam Sophie Jennifer	R11ECS		

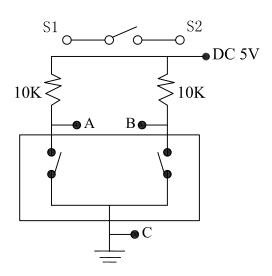
外 形 圖 Mechanical Dimensions



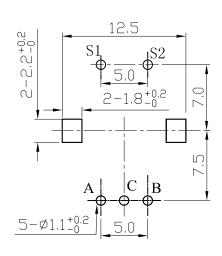


30C15P 30 15

接線圖 Circuit Explanation



安裝孔位置圖 Mounting Hole



3					PRODUCT NAME	Encoders	
1 NO	DATE	DESCRIPTION		MODEL NAME	R113ECS-10F5D1-30C15P		
DI	MENSION	TOLERANCE	SCALE		APPROVED BY	CHECKED BY	DRAWN BY
	<i>l</i> ≤10	±0.2	UNIT	mm	R&D	R&D	R & D
10)< <i>l</i> ≤ 30	±0.5	VER.		2009.06.05	2009.06.05	2009.06.05
30	< ℓ ≤ 100	±1.0	DATE	07/06/07	Jennifer	Sophie	Sam